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PHYSICS 204A

Fall, 2010

HW #2 SOLUTIONS

Physics 204A

(1)

HOMEWORK #2

$(AB)_{ij}^+ = (AB)_{ji}^*$ This is by definition i
 The matrix element of the Hermitian conjugate of an operator are the complex conjugates of the elements of the transpose.

Now

$$(AB)_{ji} = \sum_k A_{jk} B_{ki} \quad \text{by def of matrix multiplication}$$

so $(AB)_{ji}^* = \sum_k A_{jk}^* B_{ki}^*$ (properties of adding/multiplying complex numbers)

Finally $A_{jk}^* = (A^+)_k j$ (def of Hermitian conjugation)
 $B_{ki}^* = (B^+)_i k$ (def of Hermitian conjugation)

Putting this together

$$\begin{aligned} (AB)_{ij}^+ &= \sum_k (A^+)_k j (B^+)_i k \\ &= \sum_k (B^+)_i k (A^+)_k j = (B^+ A^+)_{ij} \end{aligned}$$

The last step is again the definition of matrix multiplication.

Since all components of $(AB)^+$ equal those of $B^+ A^+$

the operators themselves must be equal.

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Q

$$C_i = (A \times B)_i = \epsilon_{ijk} A_j B_k$$

a)

check it out $C_1 = \epsilon_{ijk} A_j B_k = \epsilon_{123} A_2 B_3 + \epsilon_{132} A_3 B_2$

$$C_1 = A_2 B_3 - A_3 B_2 \quad \checkmark$$

$$C_2 = \epsilon_{2jk} A_j B_k = \epsilon_{213} A_1 B_3 + \epsilon_{231} A_3 B_1$$

$$= -A_1 B_3 + A_3 B_1 \quad \checkmark$$

b)

$$\hat{A} \cdot (\vec{A} \times \vec{B}) = A_i (\vec{A} \times \vec{B})_i$$

$$= A_i \epsilon_{ijk} A_j B_k = \underbrace{\epsilon_{ijk}}_{\text{anti-symmetric}} \underbrace{A_i A_j B_k}_{\text{symmetric}}$$

$$i = 0$$

property of ϵ_{ijk}

More slowly $\epsilon_{ijk} A_i A_j B_k = -\epsilon_{jik} A_i A_j B_k$

$$= -\epsilon_{ijn} A_j A_i B_n \quad (\text{interchanging names of dummies } i, j)$$

$$= -\epsilon_{ijn} A_i A_j B_n$$

since A_i are #s which commute

since $\cancel{AB} = -\cancel{BA}$ it must vanish,

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2c

$$[A \times (B \times C)]_i = \epsilon_{ijk} A_j (B \times C)_k$$

K (sums on j, k
understood)

$$= \epsilon_{ijk} A_j \epsilon_{kem} B_e C_m$$

We need the following identity

$$\begin{matrix} \text{(sum} \\ \text{on } k \\ \text{understood}) \end{matrix} \rightarrow \epsilon_{ijk} \epsilon_{kem} = \delta_{ie} \delta_{jm} - \delta_{im} \delta_{je}$$

If we assume this is true

$$[A \times (B \times C)]_i = A_j B_e C_m (\delta_{ie} \delta_{jm} - \delta_{im} \delta_{je})$$

$$= A_m B_i C_m - C_i A_j B_j$$

$$= (\vec{A} \cdot \vec{C}) \vec{B}_i - (\vec{A} \cdot \vec{B}) \vec{C}_i$$

Since this is true for all components i

$$\vec{A} \times (\vec{B} \times \vec{C}) = (\vec{A} \cdot \vec{C}) \vec{B} - (\vec{A} \cdot \vec{B}) \vec{C}$$

Proof of identity: $\epsilon_{ijk} = 0$ unless i, j, k all different

So given K the pair i, j has only two choices for a nonzero result. Since the same K appears in ϵ_{kem}

The pair k, l can also have only two values. The only thing to check is whether the order is the same or reversed. If the same we have a perfect square and get 1, if reversed, we can exchange but pick up a - sign.

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3.

The matrix is block diagonal so consider the 2×2 blocks independently.

The lower block cannot be diagonalized !!. But fortunately it is still easy to exponentiate:

$$e^{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}} = \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + \dots}_{= \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}} \rightarrow \text{so all higher terms vanish also}$$

To deal with upper block, diagonalize it

$$\begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 - 1 = 0 \Rightarrow \lambda = \pm 1$$

$$\lambda = 1 \quad |e_1\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \lambda = -1 \quad |e_2\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\text{So transformation matrix } S = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$\text{Thus } e^{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}} = \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}}_{S^T} \underbrace{\begin{pmatrix} e^1 & 0 \\ 0 & e^{-1} \end{pmatrix}}_{e^D} \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}}_S$$

$$= \frac{1}{2} \begin{pmatrix} e^1 + 1/e^{-1} \\ e^1 - 1/e^{-1} \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} e^1 + 1/e & e^1 - 1/e \\ e^1 - 1/e & e^1 + 1/e \end{pmatrix} = \begin{pmatrix} \cosh 1 & \sinh 1 \\ \sinh 1 & \cosh 1 \end{pmatrix}$$

So whole answer is

$$\exp \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} \cosh 1 & \sinh 1 & 0 & 0 \\ \sinh 1 & \cosh 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

NB You can also do this upper block by noting $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I$

This is the trick usually used in QM texts when exponentiating spin $1/2$ Pauli matrices.

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4 First note + is true for $| \times |$ matrices, aka real numbers. (It is always a good idea to check matrix identities in this 1-dimensional limit!)

$$\begin{array}{c} \text{A} = a \\ \uparrow \quad \uparrow \\ \text{a number} \\ \text{dimension 1} \end{array}$$

$$\frac{\partial}{\partial a} \ln(\det a) = \frac{\partial}{\partial a} \ln a = \frac{1}{a} = A^{-1}$$

()

det of 1×1 matrix
= the only matrix element

inverting a $| \times |$ matrix...

Use the standard definition of derivative $\frac{f(a+\epsilon) - f(a)}{\epsilon}$

$$\left[\begin{array}{cccc} a_{11} & a_{12} & \dots & \\ a_{21} & a_{22} & & \\ & & \ddots & \\ & & & a_{ij+\epsilon} \end{array} \right]$$

By linearity of determinant the determinant with $a_{ij} \rightarrow a_{ij+\epsilon}$ is the original determinant $+ \epsilon C_{ij} \leftarrow$ the cofactor.

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4 (cont'd)

But we know $[A]_{ji}^{-1} \in \frac{c_{ij}}{\det A}$

$$\begin{aligned}
 \text{So } \frac{\partial}{\partial c_{ij}} \ln(\det A) &= \frac{1}{\epsilon} \left[\ln(\det A + \epsilon c_{ij}) - \ln(\det A) \right] \\
 &= \frac{1}{\epsilon} \left[\ln \det A \left(1 + \epsilon \frac{c_{ij}}{\det A} \right) - \ln \det A \right] \\
 &= \frac{1}{\epsilon} \left[\ln(\det A) \ln \left(1 + \epsilon A_{ji}^{-1} \right) - \ln \det A \right] \\
 &= \frac{1}{\epsilon} \left[\ln(\det A) \left[1 + \epsilon A_{ji}^{-1} \right] - \ln \det A \right] \\
 &= A_{ji}^{-1}
 \end{aligned}$$

An alternate proof can be constructed via QM perturbation theory

Alternate "Qst-style" argument: Consider $A + \epsilon \begin{pmatrix} \phi & \phi \\ \phi & 1-\phi \end{pmatrix}$ row i
and think of second matrix as "perturbation", V, col. j

$$\det(A+V) = \det A (I + A^{-1}V) = \det A \det(I + A^{-1}V)$$

$$[A^{-1}V]_{nm} = A_{nk}^{-1} V_{km} = A_{nk}^{-1} \epsilon \delta_{ik} \delta_{jm} = \epsilon A_{ni}^{-1} \delta_{jm}$$

Writing it out as a real matrix $A^{-1}V = \epsilon \begin{pmatrix} A_{1i}^{-1} \\ A_{2i}^{-1} \\ \vdots \\ \vdots \\ jm \text{ col} \end{pmatrix}$

The jth col. is filled by the ith col. of A^{-1}

$$\text{Now } \det[I + A^{-1}V] = 1 + \epsilon A_{ji}^{-1}$$

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4 cont(d)

$$\text{Thus } \det(A + V) = (\det A) \left(1 + \epsilon A_{ji}^{-1} \right)$$

The derivative is thus finally,

$$\frac{\det(A + V) - \det A}{\epsilon} = A_{ji}^{-1}$$

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5. Our original matrix for A is $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

(in the basis $|e_1\rangle, |e_2\rangle$)

You can construct the new matrix for A using the procedure of sandwiching A between S and S^T where

S describes the change in bases from $|e_i\rangle$ to $|f_j\rangle$.

But that involves recalling where to put the S and S^T .

Maybe it is less demanding on the memory simply to say

$$(A')_{11} = \langle f_1 | \hat{A} | f_1 \rangle = \frac{1}{\sqrt{2}} (++) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \frac{1}{\sqrt{2}} (++) \quad (\text{working in } |e_i\rangle \text{ basis})$$

$$= \frac{1}{2} (++) \begin{pmatrix} 1 \\ -1 \end{pmatrix} = 0$$

$$(A')_{12} = \langle f_1 | \hat{A} | f_2 \rangle = \frac{1}{2} (++) \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 1$$

$$(A')_{21} = 1 \quad (\text{by symmetry})$$

$$(A')_{22} = \langle f_2 | \hat{A} | f_2 \rangle = \frac{1}{2} (--) \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 0$$

So \hat{A} in new basis $\{|f_i\rangle\}$ is $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

6 Physical results do not depend on basis choice, first,
the possible results of measurements are eigenvalues
and they are indep of basis

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[6] cont'd Proof Suppose λ obeys $\det(A - \lambda I) = 0$

then because $\det ABC = \det A \det B \det C$ and because

The procedure for changing bases involves a unitary

transformation $A' = u A u^+$ with $u u^+ = I$ we see

$$\det(A - \lambda I) = \det u (A - \lambda I) u^+ = \det(A' - \lambda I)$$

so λ also solves $\det(A' - \lambda I) = 0$. In other words

λ is also an eigenvalue of A' .

Furthermore any expectation value is basis independent

$$\langle + | A' | + \rangle = \langle + | u^+ (u A u^+) u | + \rangle = \langle + | A | + \rangle$$

For problem 5 Note original eigenvalues of $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

are $\lambda = \pm 1$ as are eigenvalues of $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$.

If the state $|+\rangle = \begin{pmatrix} a \\ b \end{pmatrix}$ in $\{|e_i\rangle\}$ basis ~~is~~

$$\langle + | A | + \rangle = \langle \overset{*}{a} \overset{*}{b} | \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} | \begin{pmatrix} a \\ b \end{pmatrix} \rangle = |a|^2 - |b|^2$$

$$\text{Meanwhile } a|e_1\rangle + b|e_2\rangle = a \frac{1}{\sqrt{2}}(|f_1\rangle + |f_2\rangle) + b \frac{1}{\sqrt{2}}(|f_1\rangle - |f_2\rangle)$$

$$= \frac{1}{\sqrt{2}}(a+b)|f_1\rangle + \frac{1}{\sqrt{2}}(a-b)|f_2\rangle$$

$$\langle + | A' | + \rangle = \frac{1}{2} \left(\overset{*}{a} \overset{*}{b} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a & b \\ a & -b \end{pmatrix} \right) = \frac{1}{2} \left(\overset{*}{a} \overset{*}{b} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a & b \\ a & -b \end{pmatrix} \right) / \begin{pmatrix} a & b \\ a & -b \end{pmatrix}$$

$$= \frac{1}{2} ((|a|^2 - |b|^2) - a^*b + b^*a + |a|^2 - |b|^2 - b^*a + a^*b)$$

$$= |a|^2 - |b|^2$$

```
#include <stdio.h>
#include <math.h>

int main(void)
{
    int i, j;
    float M[10][10], V[10], W[10];
    FILE * fileout;

    fileout=fopen("hermione", "w");

    for (i=0; i<10; i=i+1)
    {
        V[i]=0.2*i-0.01*i*i;
    }

    for (i=0; i<10; i=i+1)
    {
        for (j=0; j<10; j=j+1)
        {
            M[i][j] = 0.5 + 20.0 / ( (i+1) + 3.0 * (j+1) );
        }
    }

    for (i=0; i<10; i=i+1)
    {
        W[i]=0.0;
        for (j=0; j<10; j=j+1)
        {
            W[i]=W[i] + M[i][j]*V[j];
        }
    }

    for (i=0; i<10; i=i+1)
    {
        fprintf(fileout, "\n%d %12.6lf %12.6lf", i, V[i], W[i]);
    }

    return 0;
}
```

$$W(7) \cong 9.566\ldots$$