

## The Fields

$$= 1 - \vec{v}_r/c \cdot \vec{R}_a$$

We obtained the potentials

$$J = 1 - \frac{1}{c} \frac{dR_a}{dt}$$

$$\phi(r,t) = qJ/R_a = \frac{q}{(R_a - \vec{v}_r/c \cdot R_a)} \quad \frac{q}{4\pi\epsilon_0}$$

$$\vec{A}(r,t) = qJ \frac{\vec{v}_r}{cR_a} = \frac{q \vec{v}_r/c}{(R_a - \vec{v}_r/c \cdot R_a)} \quad \frac{\mu_0}{4\pi} q$$

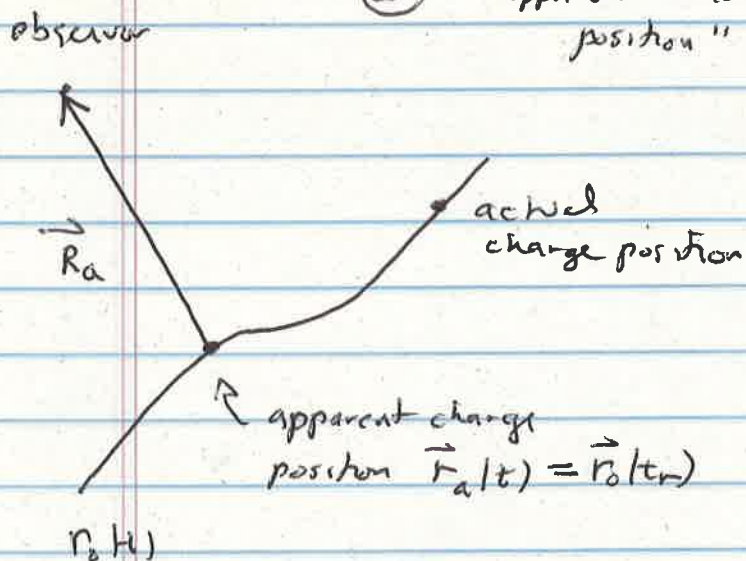
These are in Gaussian units.

Recall the definitions  $\vec{R}_a(t) = \vec{r} - \vec{r}_a(t_r) = \vec{r} - \vec{r}_a(t)$

↑  
vector from  
source to observer

↑  
retarded time  
↑  
"apparent  
position"

⊖ "apparent relative  
position"



$R_a$

There are 3 pieces to  $\vec{E}$ . The first two,  $\vec{E}_1$  and  $\vec{E}_2$ , originate in  $\vec{\nabla}\phi$  while the third,  $\vec{E}_3$ , is from  $\frac{\partial \vec{A}}{\partial t}$

$$\phi(\vec{r}, t) = q \int d^3r' \int dt' \frac{1}{|\vec{r}-\vec{r}'|} \delta(\vec{r}-\vec{r}_0(t')) \delta(t'-t+\frac{1}{c}R)$$

If  $\vec{\nabla}\phi$  acts on  $1/R = 1/|\vec{r}-\vec{r}'|$  we get  $\hat{R}/R^2$  so

$$\vec{E}_1(\vec{r}, t) = q \int d^3r' \int dt' \frac{\hat{R}}{R^2} \delta(\vec{r}-\vec{r}_0(t')) \delta(t'-t+\frac{1}{c}R)$$

But  $\vec{\nabla}\phi$  can also act on the time delta function. Using the chain rule

$$\frac{d}{dx} \delta(t'-t+\frac{1}{c}R) = \delta'(t'-t+\frac{1}{c}R) \frac{1}{c} \frac{(x-x')}{R} \leftarrow \text{x component of } \hat{R} = \frac{\hat{R}}{R}$$

Therefore

$$\begin{aligned} \vec{E}_2(\vec{r}, t) &= \frac{q}{c} \int d^3r' \int dt' \frac{\hat{R}}{R} \delta(\vec{r}-\vec{r}_0(t')) \delta'(t'-t+\frac{1}{c}R) \\ &= \frac{q}{c} \frac{d}{dt} \int d^3r' \int dt' \frac{\hat{R}}{R} \delta(\vec{r}-\vec{r}_0(t')) \delta(t'-t+\frac{1}{c}R) \end{aligned}$$

Finally the  $-\frac{1}{c} \frac{d\vec{A}}{dt}$  term,

$$\vec{A} = \frac{\mu_0 q}{4\pi} \int d^3r' \int dt' \frac{\vec{v}_0(t')}{|\vec{r}-\vec{r}'|} \delta(\vec{r}'-\vec{r}_0(t')) \delta(t'-t-\frac{1}{c}R)$$

$$-\frac{1}{c} \frac{d\vec{A}}{dt} = -\frac{\mu_0 q}{4\pi c} \frac{d}{dt} \int d^3r' \int dt' \frac{\vec{v}_0(t')}{R} \delta(\vec{r}'-\vec{r}_0(t')) \delta(t-t'-\frac{1}{c}R)$$

If we put  $\vec{E}_2$  and  $\vec{E}_3$  together we obtain

$$\begin{aligned}\vec{E}_{23} &= q \frac{1}{c} \frac{d}{dt} \int d^3r' \int dt' \frac{\hat{R} - \vec{v}(t')/c}{R} \delta(\vec{r}' - \vec{r}_a(t')) \delta(t - t' - R/c) \\ &= q \frac{1}{c} \frac{d}{dt} \left[ \int \frac{\hat{R}_a - \vec{v}_a/c}{R_a} \right]\end{aligned}$$

This last step follows from mathematics identical to the  
find integrations ~~under~~ over  $\int d^3r' \int dt'$  in obtaining  $\vec{E}_1$ , the

key step of which was  $\delta(t - t' - R/c) = \int \delta(t' - t_r)$

We want to understand how many time derivatives there

are in the different pieces of  $\vec{E}$ .  $\vec{E}_1$  gives the only piece

with zero time derivatives  $\vec{E}_1 = \int \frac{\hat{R}_a}{R_a^2} =$  with  $\int = 1 - \frac{1}{c} \frac{dR_a}{dt}$

$$\vec{E}^{(0)} = q \frac{\hat{R}_a}{R_a^2}$$

The piece with one time derivative comes from  $\vec{E}_1$  and <sup>part of</sup> the  $\frac{\hat{R}_a}{R_a}$  piece of  $\vec{E}_3$

$$\begin{aligned}\vec{E}^{(1)} &= -q \frac{1}{c} \frac{\hat{R}_a}{R_a^2} \frac{dR_a}{dt} + q \frac{d}{dt} \frac{\hat{R}_a}{R_a} \\ &= q \frac{R_a}{c} \frac{d}{dt} \left( \frac{\hat{R}_a}{R_a^2} \right)\end{aligned}$$

$$\text{Since } \frac{d}{dt} \frac{\hat{R}_a}{R_a} = \frac{d}{dt} \left( \frac{\hat{R}_a}{R_a^2} R_a \right) = \frac{d}{dt} \left( \frac{\hat{R}_a}{R_a^2} \right) R_a + \frac{\hat{R}_a}{R_a^2} \frac{dR_a}{dt}$$



LWF 9

The term with two time derivatives comes from the

other part of the  $\frac{\hat{R}_a}{R_a}$  term in  $\vec{E}_{23}$  and the  $\vec{v}_r/c$  term in  $\vec{E}_{23}$

$$\vec{E}^{(2)} = q/c^2 \frac{d}{dt} \left[ -\frac{\hat{R}_a}{R_a} \frac{dR_a}{dt} + \frac{1}{R_a} \frac{d\hat{R}_a}{dt} \right]$$

As for  $\vec{E}^{(1)}$ , the two terms can be combined using the product rule

from  $\frac{1}{c} \frac{dR_a}{dt}$  piece of  $\vec{J}$  since  $R_a^{(R)} = r - r_0(t_r)$

$$\frac{v_r}{c} = \frac{1}{c} \frac{dr_0}{dt} \Big|_{t_r} = -\frac{1}{c} \frac{dR_a}{dt} \Big|_{t_r}$$

$$\frac{d\hat{R}_a}{dt} = \frac{d}{dt} \frac{1}{R_a} \vec{R}_a$$

$$= -\frac{1}{R_a^2} \frac{dR_a}{dt} \vec{R}_a + \frac{1}{R_a} \frac{d\vec{R}_a}{dt}$$

$$- \frac{1}{R_a} \frac{dR_a}{dt} \hat{R}_a$$

$$\vec{E}^{(2)} = q/c^2 \frac{d}{dt} \frac{d\hat{R}_a}{dt}$$

All together

first derived by Feynman

$$\vec{E} = q \frac{\hat{R}_a}{R_a^2} + q \frac{R_a}{c} \frac{d}{dt} \frac{\hat{R}_a}{R_a^2} + q \frac{1}{c^2} \frac{d^2 \hat{R}_a}{dt^2}$$

Add  $\frac{1}{4\pi\epsilon_0}$

Heaviside-Feynman formulas for fields

Similar sort of algebra

$$\vec{B} = q \frac{\vec{v}_a \times \hat{R}_a}{c R_a^2} + q \frac{d}{dt} \frac{\vec{v}_a \times \hat{R}_a}{c^2 R_a} = \hat{R}_a \times \vec{E}$$

$$\frac{1}{c} \rightarrow \frac{\mu_0}{4\pi}$$

due to Heaviside  $\frac{1}{c} \hat{R}_a \times \vec{E}$

Physical interpretation of Feynman formulae

$$\vec{E} = q \frac{\hat{R}_a}{R_a^2} + q \frac{R_a}{c} \frac{d}{dt} \frac{\hat{R}_a}{R_a^2} + q \frac{1}{c^2} \frac{d^2}{dt^2} \hat{R}_a$$

③

Coulomb field due to  $q$  at apparent (retarded) position

time derivative of field times delay so partially "corrects" first term

Radiation field we will show  $\sim 1/R$  Dominant at large  $R$  Has some  $1/R^2$  pieces

Very close to instantaneous Coulomb field, i.e. Coulomb field evaluated at actual position

There is also a "Lienard-Wiechert" form for  $\vec{E}$  and  $\vec{B}$  which separates  $\vec{E}$  into  $1/R$  and  $1/R^2$

$$\vec{E} = \frac{q(1 - v_r^2/c^2)}{(R_a - \frac{\vec{v}_r}{c} \cdot \vec{R}_a)^3} (\vec{R}_a - \frac{\vec{v}_r}{c} R_a)$$

only term is  $\vec{v}_r = 0$  (no acceleration) compare to constant  $\vec{v}$  calculation of last week

$\frac{1}{4\pi\epsilon_0}$

$$+ \frac{q}{c^2 (R_a - \frac{\vec{v}_r}{c} \cdot \vec{R}_a)^3} (\vec{v}_r \times (\vec{R}_a - \frac{\vec{v}_r}{c} R_a)) \times \vec{R}_a$$

$$\vec{B} = \hat{R}_a \times \vec{E}$$

$$R_a - \frac{\vec{v}_r}{c} \cdot \vec{R}_a \rightarrow 0 \text{ if } \vec{v}_r \parallel \vec{R}_a$$

and  $v_r \neq c$

$1/c$

Synchrotron radiation concentrated in direction of motion